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# Transverse Vibrations of a Shallow Spherical Dome

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Los Angeles, California

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# **FOREWORD**

This report is published by the Aerospace Corporation, El Segundo, California, under Air Force Contract AF 04(695)-1001. The report was authored by M. H. Lock and H. A. Malcom, of the Applied Mechanics Division and Electronics Division, respectively, El Segundo Technical Operations, and by J.S. Whittier, Aerodynamics and Propulsion Research Laboratory, Laboratories Division, Laboratory Operations.

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Project Officer

# ABSTRACT

It is shown that the nondimensional roots of the frequency equation for nonsymmetric transverse vibrations of a clamped-edge shallow spherical dome depend upon a single shell geometric parameter. Numerical values of the frequency parameter are given in tabular and graphical form for an extensive range of shell geometries and mode numbers. A simplified version of the frequency equation is also presented and its accuracy discussed.

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# INTRODUCTION

Kalnins [1] has treated the nonsymmetric mode vibrations of a clampededge shallow spherical shell and has presented frequency data for a limited
range of the geometric parameters a/R and a/h, where a, h and R denote the
base radius, wall thickness and radius of curvature of the shell, respectively.
Kalnins included both transverse and longitudinal (i.e., in-plane) inertial
forces in his analysis and compared transverse mode frequencies that were
calculated with and without the effect of the longitudinal inertial forces. For
the range of parameters treated, he found that these inertial forces produced
little change in the transverse mode frequencies.

The purpose of the present Note is to extend the range of calculated frequency data for this type of shell. First it is shown that the frequency equation can be expressed in terms of a single geometric parameter when the longitudinal inertial forces are neglected. The roots of this form of the frequency equation are then determined for an extensive range of mode numbers and shell geometry.

Numbers in brackets designate References.

### ANALYSIS

When longitudinal inertial forces are neglected, the equations of motion governing the free vibrations of a shallow spherical shell are [2]

$$D\nabla^2\nabla^2w + \frac{1}{R}\nabla^2F + \rho h \frac{\partial^2w}{\partial t^2} = 0$$
 (1)

$$\nabla^2 \nabla^2 \mathbf{F} - \frac{\mathbf{E}\mathbf{h}}{\mathbf{R}} \nabla^2 \mathbf{w} = 0 \tag{2}$$

where  $\nabla^2$  is the Laplacian operator,  $w(\cdot,\theta,t)$  is the transverse displacement of the shell (see Fig. 1) and F is an Airy stress function. This stress function is related to the transverse displacement  $w(r,\theta,t)$  and to the inclane displacement components  $u_{\theta}(r,\theta,t)$  and  $u_{r}(r,\theta,t)$ , reference [3]. The parameters E and  $\rho$  are Young's modulus and the mass density of the shell material, respectively. The bending stiffness  $D = \sum h^3/12(1-v^2)$ , where v denotes Poisson's ratio. To determine the vibration frequencies, solutions of the form

$$(w, F) = \begin{cases} \sin n\theta \\ \cos n\theta \end{cases} \left[ W_n(r), F_n(r) \right] e^{i\omega t}$$
 (3)

are substituted into the equations of motion. The resulting ordinary differential equations are solved under the condition that the stresses and displacements are finite at the origin. Application of the appropriate boundary conditions results in an equation for the frequencies of the shell. In the case of a shell with clamped edges, the boundary conditions are

$$w(a, \theta, t) = u_{\theta}(a, \theta, t) = u_{r}(a, \theta, t) = 0$$
 (4a)

$$\frac{\partial w}{\partial r} (a, \theta, t) = 0$$
 (4b)

and the resulting frequency equation is 2.

$$\left[II_{n} - 4n\left(\frac{a}{R}\right)^{2}\right] I_{n}(\mu) J_{n-1}(\mu) - \left[N_{n} + 4n\left(\frac{a}{R}\right)^{2}\right] J_{n}(\mu) I_{n-1}(\mu) + \left(\frac{a}{R}\right)^{2} \left[\frac{8n^{2}}{\mu} J_{n}(\mu) I_{n}(\mu) + 2\mu J_{n-1}(\mu) I_{n-1}(\mu)\right] = 0$$
 (5)

where

$$N_{n} = \frac{\mu^{2}}{2(1+v)(n+1)} \left[ (3-v) \Omega^{2} - 4\left(\frac{a}{R}\right)^{2} \right]$$

$$\mu^{4} = i2(i-v^{2}) \left(\frac{a}{h}\right)^{2} \left[\Omega^{2} - \left(\frac{a}{R}\right)^{2}\right]$$

$$\Omega^{2} = \frac{\rho a^{2} \omega^{2}}{F}$$

The  $J_n(\mu)$  and  $I_n(\mu)$  are Bessel functions and modified Bessel functions of the first kind; n denotes the number of nodal diameters and  $\omega$  is the frequency of vibration.

This equation was employed by Kalnins [1] for cases where the longitudinal inertial forces were neglected.

To extend the range of calculated frequency data for this type of shell, we first note that the nondimensional roots  $\mu_{n,m}$  (where  $m \ge 1$  is the rank of the root) may be obtained as functions of a single geometric parameter rather than in terms of the ratios a/R and a/h. To show this, we introduce the geometric parameter  $\lambda$  used in the buckling theory of such shells. Substitution of

$$\lambda^4 = 12(1-v^2) a^4/R^2 h^2 \tag{6}$$

into equation (5) gives the following frequency equation

$$\left\{ \mu^{2} \left[ -1 + \frac{(3-v)}{(1+v)} \left( \frac{\mu}{\lambda} \right)^{4} \right] - 8n(n+1) \right\} \mu I_{n}(\mu) J_{n-1}(\mu)$$

$$- \left\{ \mu^{2} \left[ -1 + \frac{(3-v)}{(1+v)} \left( \frac{\mu}{\lambda} \right)^{4} \right] + 8n(n+1) \right\} \mu I_{n-1}(\mu) J_{n}(\mu)$$

$$+ 16 n^{2} (n+1) J_{n}(\mu) I_{n}(\mu) + 4(n+1) \mu^{2} J_{n-1}(\mu) I_{n-1}(\mu) = 0$$
(7)

For a specified value of n, the roots of this equation depend only upon Poisson's ratio v and the geometric parameter  $\lambda$ . In order to encompass a wide range of shell configurations, calculations were performed for  $\lambda \leq 20$  and  $1 \leq n \leq 20$ , with v = 0.3. The resulting roots  $\mu_{n,m}$  are presented in Table 1 for values of the rank m up to 3. Some of the tabulated results are presented in graphical form in Fig. 1. This figure is particularly illuminating since it clearly shows that the roots tend to increase linearly with increase in the number of nodal diameters when n is sufficiently large. The figure also indicates that the roots tend to become independent of  $\lambda$  as n becomes larger. This behavior is related to the fact

Table 1. Frequency Parameter  $\mu_{n, m}$ 

		·						
23.	m	. 0	2.5	5.0	7.49	10.0	15.0	20.0
i	1 2 3	4.611 7.779 10.958	4.628 7.801 10.958	4.865 7.828 10.964	5.555 7.956 10.989	6.383 8.3 <b>8</b> 9 11.068	7.006 9.988 11.196	7. 103 10. 416 13. 416
2	1 2 3	5.905 9.197 12.402	5.912 9.198 12.402	6.005 9.213 12.406	6.346 9.279 12.423	6.964 9.478 12.473	7. 971 10. 635 12. 896	8.234 11.520 14.209
3	1 2 3	7. 144 10. 537 13. 795	7. 146 10. 537 13. 795	7. 190 10. 546 13. 798	7.364 10.585 13.810	7.749 10.695 13.843	8.780 11.399 14.085	9.279 12.452 14.952
4	1 2 3	8.347 11.837 15.150	8.348 11.837 15.151	8.371 11.843 15.152	8.468 11.867 15.160	8.701 11.935 15.184	9.549 12.365 15.340	10.233 13.282 15.878
5	4 4 3	9.526 13.107 16.475	9.527 13.108 16.476	9.540 13.111 16.477	9.598 13.128 16.483	9.743 13.172 16.500	10.375 13.450 16.608	11.115 14.141 16.956
6	1 2 3	10.687 14.355 17.776	10.688 14.355 17.777	10.696 14.358 17.778	10.732 14.369 17.782	10.827 14.400 17.795	11.282 14.589 17.873	11.971 15.087 18.113
7	1 2 3	11.835 15.585 19.058	11.835 15.585 19.058	11.841 15.587 19.060	11.865 15.595 19.062	11.928 15.617 19.072	12.256 15.751 19.131	12.842 16.110 19.304
8	1 2 3	12.971 16.799 20.323	12.971 16.799 20.323	12.975 16.800 20.324	12.992 16.806 20.327	13.036 16.827 20.334	13.274 16.921 20.379	13.751 17. <b>\$</b> 86 20.509
9	1 2 3	14.098 18.000 21.574	14.098 18.000 21.574	14.101 18.000 21.574	14.113 18.006 21.576	14.145 18.018 21.582	14.320 18.092 21.618	14.701 18.292 21.718
10	1 2 3	15.218 19.190 22.812	15.218 19.191 22.812	15. 220 19. 191 22. 812	15.228 19.195 22.814	15.252 19.204 22.819	15.383 19.261 22.847	15.685 19.415 22.926
11	1 2 3	16.330 20.371	16.330 20.371	16. 332 20. 371	16.338 20.375	16.356 20.382	16.456 20.426	16.695 20.547
12	1 2 3	17.437 21.544	17.437 21.544	17.439 21.544	17.444 21.546	17.457 21.552		17.725 21.684
13	1	18.539	18.539	18.540	18.544	18.555	18.616	18. 768
14	1	19.637	19.637	19.638	19.641	19.649	19.699	19.821
15	1	20.730	20.730	20.731	20.733	20.740	20.780	20.880
16	1	21.820	21.820	21.820	21.822	21.828	21.860	21.943
17	1	22. 906	22.906	22.907	22.908	22.913	22.939	23.008
18	1	23.990	23.990	23.990	23.992	23.995	24.017	24.075
19	1	25.071	25.071	25.071	25.072	25.075	25,093	25. 142
20	1	26. 149	26. 149	26.149	26.150	26.153	26. 168	26, 209

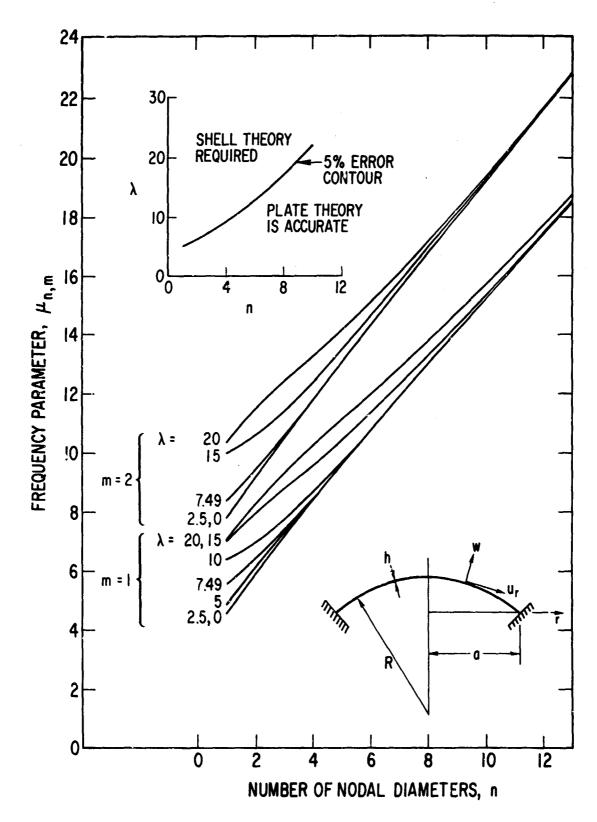


Figure 1. Frequency Parameter  $\mu_{n,m}$ ;  $\nu = 0.3$ 

that the  $\mu_{n,m}$  become large as n is increased. When the ratio  $\mu/\lambda$  has become sufficiently large, the frequency equation (7) takes the following approximate form

$$I_n(\mu) J_{n-1}(\mu) - I_{n-1}(\mu) J_n(\mu) = 0$$
 (8)

which is independent of the parameter  $\lambda$ . This equation is the frequency equation for the transverse vibrations of a clamped circular plate [4]. The roots of this equation are presented in Table 1 (see the  $\lambda$  = 0 column) and are also shown in Fig. 1. A comparison of the results from equations (7) and (8) shows that the fundamental roots differ by 5% or less for the region of the  $\lambda$ -n plane indicated in the inset of Fig. 1. The region of agreement appears to be larger for the higher modes (m = 2, 3). Thus the roots of the plate equation provide an excellent approximation to the results for the shell over a considerable range.

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